WEST Search History

Hide Items Restore Clear Cancel

DATE: Thursday, July 22, 2004

Hide?	<u>Set</u> Name	Query	<u>Hit</u> Count
	DB=U	SPT, USOC, EPAB, JPAB, DWPI, TDBD; PLUR=YES; OP=OR	
1	L5	L4 and (filter\$3 or address\$2 or tim\$3)	17
	L4	L3 and compensat\$	17
	L3	L2 and (filter\$3 or address\$3 or phase\$1 or add\$3 or sum\$4)	33
	L2	L1 same (compensat\$ or adjust\$5 or correct\$) same (memory near5 (first or second))	43
	L1	(disturb\$5 or eccentric\$4) same (detect\$ or error\$ or servo\$5 or position\$3) same (actuat\$3 or mov\$3 or driv\$3)	178845

END OF SEARCH HISTORY

WEST Search History

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DATE: Thursday, July 22, 2004

Hide?	<u>Set</u> <u>Name</u>	Query	Hit Count		
DB=USPT, USOC, EPAB, JPAB, DWPI, TDBD; PLUR=YES; OP=OR					
1	L23	L22 and L21	1		
	L22	L20 and 360/78.\$.ccls.	2		
	L21	L20 and 360/77.\$.ccls.	. 6		
	L20 <i>DB=0</i>	(learning adj2 control\$) same ((track\$1 or error\$ or servo\$) with position\$) USPT; PLUR=YES; OP=OR	57		
1	L19	L18 and ((track\$1 or error\$ or servo\$) with position\$)	6		
	L18	L17 and (sum\$ or add\$3 or subtract\$ or different\$)	6		
	L17	L16 and (compensat\$ or offset\$)	6		
	L16	L15 and memory	7		
	L15	L7 and filter\$	13		
	L14	L7 and fliter\$. 0		
П	L13	L7 and interpolat\$	1		
	L12	L8 and interpolat\$	0		
Π	L11	L8and interpolat\$	44109		
	L10	L9 and interpolat\$	0		
	L9 ·	L8 and (learning adj3 control\$4)	2		
	L8	L7 and (address\$ or fall\$3 or ris\$3)	9		
П	L7	6628579.pn. or 5907450.pn. or 6661599.pn. or 6208949.pn. or 5995316.pn. or 6459663.pn. or 6417983.pn. 6404581.pn. or 6347017.pn. or 6278898.pn. or 5729514.pn. or 5784272.pn. or 5757641.pn. or 5402400.pn. or 5347447.pn. or 5233586.pn.	16		
	L6	6628579.pn. or 5907450.pn. or 6661599.pn.	3		
	DB=U	USPT, USOC, EPAB, JPAB, DWPI, TDBD; PLUR=YES; OP=OR			
	L5	L4 and (filter\$3 or address\$2 or tim\$3)	17		
1	L4	L3 and compensat\$	17		
	L3	L2 and (filter\$3 or address\$3 or phase\$1 or add\$3 or sum\$4)	33		
	L2	L1 same (compensat\$ or adjust\$5 or correct\$) same (memory near5 (first or second))	43		
П	L1	(disturb\$5 or eccentric\$4) same (detect\$ or error\$ or servo\$5 or position\$3) same (actuat\$3 or mov\$3 or driv\$3)	178845		

END OF SEARCH HISTORY

Best Available Copy